1-999: User Defined Errors

User defined errors are errors generated by the user program with an ERROR statement. It is recommended that unique user generated errors utilize error numbers from 1 to 999 to prevent possible overlap with future releases of MotionBASIC[®].

1000 - 1099: Syntax Errors

Syntax errors are caused by an incorrect, unexpected, or missing keyword, parameter, or delimiter. They can be fixed by editing the program at the line that the error exists.

1000: Syntax error 1001: Invalid line number 1002: Missing subscript 1003: Read-only variable 1004: MOVE syntax error 1005: Error in data 1006: Expected command 1007: Garbage after statement 1008: Too many parameters 1009: Not enough parameters 1010: Expected expression 1011: Expected user variable name 1012: Expected variable name -----1014: Expected a number 1015: Expected a line number or label -----

1017: Expected comma 1018: Expected comma or semicolon 1019: Expected semicolon 1020: Expected left paren 1021: Expected right paren 1022: Expected equal sign 1023: Expected GOTO 1024: Expected THEN 1025: Expected TO 1026: Expected ON, OFF or STOP 1027: Expected a numeric variable 1028: Expected an EVENT input signal 1029: GEAR syntax error -----1031: Expected IN or AT to specify gear ratio 1032: Expected a string variable

1033: Invalid user variable or resource

1100 - 1199: Program Structure Errors

Program structure errors are caused by an unexpected or missing statement. They can be fixed by adding, deleting, or changing a line in the program.

1101: Missing equal sign or 1117: Statement cannot be nested undefined line number/label 1118: Statement not allowed inside a FOR loop 1102: FOR without NEXT 1119: Statement not allowed 1103: NEXT without FOR 1120: Unexpected end of module 1104: GOSUB without RETURN 1121: RESUME without thread 1122: CANNOT END AN ERROR THREAD 1105: RETURN without GOSUB 1106: WHILE without WEND 1123: RETURN from EVENT cannot specify a 1107: WEND without WHILE label 1108: ELSE/ELSEIF without IF-THEN block ------1109: Missing ENDIF 1199:Statement not allowed during SEIZE 1110: RESUME without error with timeout 1111: Out of data 1112: Excess data 1113: Function not found 1114: Duplicate definition 1115: Block structure must be the first statement 1116: Missing FIELD statement

1200 - 1299: Expression Errors

Expression errors are caused by a numeric or string value out of range, or an incorrect variable type. They can be fixed by changing the value, or type of variable/constant.

1201: Illegal function call 1202: Numeric overflow 1203: Subscript out of range 1204: Division by zero 1205: Type mismatch 1206: String too long 1207: String formula too complex 1208: Numeric underflow 1209: Invalid numeric operation 1210: Precision error 1211: Integer division by zero 1212: Parameter out of range 1213: Expected string 1214: Expected integer 1215: Expected long 1216: Empty string

1218: Range error from INPUT@ high limit 1219: Range error from INPUT@ low limit 1220: Expected a positive number 1221: No such Ormec variable 1222: Array not dimensioned 1224: Expected set 1225: Invalid set element 1226: Record length exceeded 1227: Invalid FIELD variable 1228: NV prefix too long 1229: Cannot change NV prefix 1230: Illegal NV variable type 1231: Invalid thread ID ¹²³²: Uninitialized Variable

1217: Function evaluation error

1300 - 1399: I/O Errors

I/O Errors are caused by an error during an attempted I/O operation. They are not caused by an error in the I/O statement itself.

1301: File not found 1302: Cannot create file 1303: Input past end 1304: Bad filename 1305: Direct statement in file _____ 1306: Invalid baud rate 1307: Cannot open device/file 1308: Device/File already open 1309: Device not open 1310: Device write failed 1311: Cannot close device 1312: Device read failed 1313: Illegal discrete I/O statement 1314: Device not opened for writing 1315: Device not opened for reading 1316: EIO.MODE@ not set for Pamux 1317: Timeout during AIO access 1318: Illegal analog I/O statement 1319: Invalid IO.MODE@ configuration 1320: IO.MODE@ for Pamux write only 1321: Too many timed DIO@ pts active 1322: No PC Card installed _____

1324: PC Card is write protected 1325: Invalid path 1326: Disk full

1329: File save failed 1330: PC Card may contain data 1331: Unable to FORMAT PC Card _____

1334: Bad file mode 1335: Device seek failed 1336: ITM-270 Communications Failure 1337: Path/File Access Error 1338: Cannot open protected file 1339: Disk is full 1340: Cannot format a system card 1341: Invalid drive specified 1342: System card not found 1343: Changing baud not allowed with TCP/IP ^{*}1344: Cannot configure I/O for M-Stop operation 1345: M-Stop configuration conflicts with hdw 1346: I/O pair not configured M-Stop operation ^{*}1347: I/O point configured for M-Stop operation

1400 - 1599: (Reserved)

1600 - 1699: Motion Errors

Motion errors are caused by a situation preventing the completion of a motion as prescribed by the motion statement.

1601: Velocity out of range 1602: Accel or decel out of range _____ 1604: Illegal motion sequence -----1606: Invalid axis ID 1607: Axis mode is incorrect 1624: Unprepared Motion ID 1608: Fwd software travel limit 1609: Rev software travel limit 1610: Illegal while DSP busy 1612: Specified gear ratio is out of range ** 1629: Temperature sensor configuration error ** 1630: Brake Mode is incorrect _____ 1614: Fwd hardware travel limit 1615: Rev hardware travel limit 1616: DSP queue too full for REPEAT 1617: Hardware travel limit Configuration Error

1700 - 1799: (Reserved)

1800 - 1899: System Errors

System errors are caused by a system or hardware limitation, incorrect mode, etc.

1801: Out of memory 1802: Illegal direct 1803: Out of string space` 1804: Cannot continue 1805: ABORT or Ctrl-Break detected 1806: Input buffer overflow 1807: Too many levels of nesting 1808: Illegal indirect _____

1810: Program buffer write protected 1811: Token buffer overflow 1812: Illegal while FAULT@ is non-zero 1813: Illegal while ESTOP.OK@ is False 1832: Thread already assigned another EVENT 1814: Illegal while AFAULT@ is non-zero **1833: MotionData Configuration Error 1815: MotionDATA not available 1816: Program buffer read protected 1817: Out of NV memory 1818: No NV memory installed

1819: Out of program memory

- 1618: Project file contains non-existent axis id
- 1619: Invalid Motion ID
- 1620: Duplicate Motion ID was specified
- 1621: Cannot Prepare Motion
- 1622: Out of Motion Memory on Axis 1623: Incompatible Prepared Motion
- 1625: Specified axis ID not in project file
- 1626: Blend would exceed last target distance
- 1627: Blending distance illegal during final decel
- ** 1628: Over temperature condition exists
- ** 1631: Not supported for auxiliary axis

1820: Function/Command Not Supported

- 1821: Too many HOLDs without a RELEASE 1822: RELEASE without HOLD _____
- 1824: HOLD.CNT@ is non-zero when SEIZEing
- 1825: Could not create a thread
- 1826: Illegal Operation using D-Mode Thread ID
- 1827: Thread state must be STOPPED
- 1828: Illegal while MSTOP.OK@ is FALSE
- 1829: Illegal while MFAULT@ is non-zero
- 1830: No Type change from EVENT to ERROR
- 1831: No Type change from ERROR to EVENT
- **1834: ServoWire Communications Timeout
- **1835: Unsupported Option Error
- **1836: MotionDesk/MotionBASIC Incompatibility
 - No FTP Allowed

1900 - 1999: Controller Fault Errors ... NO FAULT relay will open.

System errors are Caused by a hardware limitation of the controller. 1900-1909 are reserved for user generated controller fault errors, which permits the user to issue an error which opens the no-fault relay. The user generated controller fault error is reported in the FAULT@ variable bit 8... Machine Fault.

1910: E-Stop OK input open 1911: Axis fault 1912: Internal error 1913: DSP axis module failure 1914: String space corrupted! 1915: Incompatible MBX version 1916: MBX out of memory _____

1918: MBX not installed 1919: Checksum Error 1920: MotionCREDIT Verification Failure

- 1921: M-Stop OK input open
- **1922: ServoWire network fault

_____ 1998: Watchdog timeout

1999: Temporary power loss

9000 - 9999: MBX Errors

Although not strictly a part of MotionBASIC, but rather associated with typical MotionBASIC Extensions, MBX's, the following errors are also listed.

- 9001: Register not mapped 9002: Invalid map 9003: Timeout accessing variable 9004: Register modified 9005: DH communications card error 9006: DH card or driver not installed 9007: Invalid PLC5 file address 9008: Driver not installed 9009: Not allowed as Modbus slave 9010: Not allowed as MotionNET slave 9011: DIO point already mapped 9012: Illegal while communications are enabled 9013: Invalid configuration 9014: Lost remote communications 9015: Task already active
- 9016: Timeout waiting for reply 9017: Error in reply message
- 9018: Incompatible remote I/O configuration
- 9019: Remote I/O not configured
- 9020: Communications are disabled

- 9021: RTU Mode requires 8 data bits 9021: RTU Mode requires 8 data bits 9022: Dancer at limit
- _____
- 9027: Requested MD.MODE@ value incompatible with other axis
- -----
- 9030: Requested values for MODE@ and MD.MODE@ are incompatible 9031: Minimum Tension Limit
- 9032: Maximum Tension Limit